

## Integrating Force Feedback Into Minimally Invasive Robotic Surgery

In this video, students at Drexel University describe an approach for integrating force feedback into existing minimally invasive robotic surgery systems, such as the da Vinci System. This work was performed as a senior design project at Drexel University during the 2008-2009 academic year.

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<http://www.surgicalproductsmag.com/videos/2009/11/integrating-force-feedback-minimally-invasive-robotic-surgery>